

# LR Mate 200iD/7H



Max. load capacity  
at wrist: 7 kg



Max. reach:  
717 mm

# FANUC

Robot			Max. load capacity at wrist (kg)	Reach (mm)	Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						Moments (N-m)/Inertia (kg-m <sup>2</sup> )			Protection		
Series	Version	Type						J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6	J4 Moment/ Inertia	J5 Moment/ Inertia	J6 Moment/ Inertia	Average Power consumption (kW)	Body standard/optional	Wrist & J3 arm standard/optional
LR Mate 200	iD	7H	7	717	5	±0.01**	24	340 (360)	245	420	250	720	-	450	380	520	545	1500	-	16.6/47	4/046	-	0.5	IP67/ IP69K	IP67/ IP69K

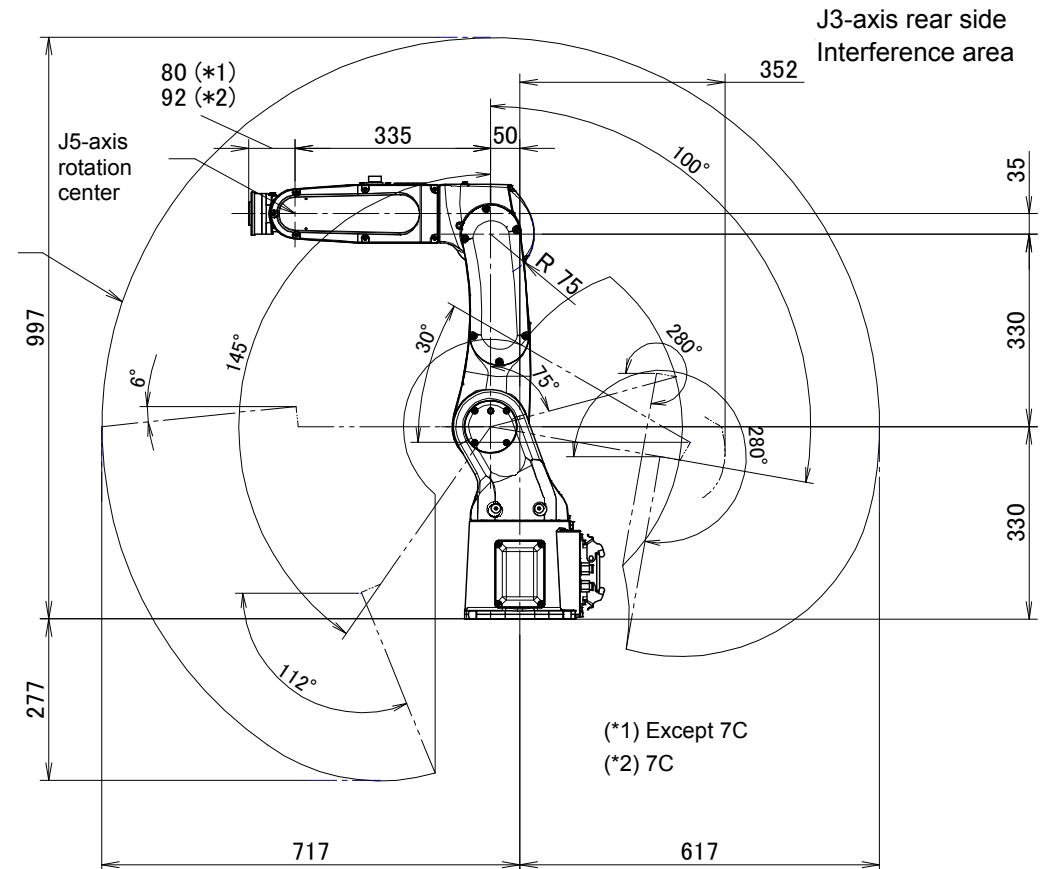
[option] ● standard ○ on request - not available ( ) with hardware and/or software option \*\* Based on ISO9283

LR Mate 200iD/7H 5-axis, [2 integrated solenoid valves]



LR Mate 200iD

Operating space  
of J5-axis rotation  
center



» If applied load on the robot exceeds 5kg when the robot is installed on an angle, the operating area is limited by the mount angle. If payload is less than 5kg, there is no restriction of the operating space.